

Numerical analysis of double inlet two-stage inertance pulse tube cryocooler

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Abstract

Stirling-type Pulse Tube Cryocoolers (PTC) are designed to meet present and upcoming commercial requirements and needs with durability and low vibrations. Multistaging in Stirling type PTC is one of the major developments reported in recent times for low-temperature achievement, due to improved performance over a period of time. The current study aims to define the methodology for numerical assessment of Double Inlet Two-Stage Pulse Tube Cryocooler (DITSPTC) to achieve cryogenic temperature of 20 K. This paper performs Computational Fluid Dynamics (CFD) simulation of PTC for defining the methodology using the CFD software package and then the same methodology is extended for the analysis of DITSPTC. The system simulations are performed with frequency of 70 Hz and average pressure of 20 bar. The minimum temperatures obtained from simulations are 95 K and 20 K at the first and second stage respectively.

Keywords

Pulse tube cryocooler, CFD, Cryogenic temperature, Multistaging, Double inlet valve.

1.Introduction

The basic Pulse Tube Cryocoolers (PTC) was invented by Gifford and Longworth [1]. A compressor is used to drive this system which does pressurization and depressurization of working gas to obtain the required effect in the system. Continuous analysis and subsequent enhancement in the performance of PTC has done in the last few decades. Mikulin et al. [2] introduced the orifice type PTC.

The addition of an orifice valve results in Cold End Heat Exchanger (CHX) temperature of 105 K using air as the working fluid. Based on phase shift, design variations were proposed as double inlet Orifice Pulse Tube Cryocooler (OPTC) [3] and Inertance Tube Pulse Tube Cryocooler (IPTC) [4]. They proposed that the performance of the basic PTC can be enhanced by adding a phase-shifting mechanism as shown in *Figure 1*. The setting of a double inlet valve governs the performance of the cryocooler to a great extent. The distribution of the total gas from the compressor into the stages is crucial as it mainly depends on the area available through the double inlet valve. Accordingly, the mass flow rate through the valve is the governing factor.

Hu et al. [5] done numerical and experimental studies of DIPTC and IPTC. They determined that optimal phase shift cannot be obtained by the use of an inertance tube only for low cooling power, but can provide an optimum phase shift for PTCs with high cooling power. Double inlet valve incorporated to obtain optimal phase shift in case of low cooling power PTC. Roy and Kundu [6] done the thermodynamic analysis of basic PTC, OPTC, and DIPTC and shown that the DIPTC gives better cooling performance than basic PTC, OPTC.

Multistaging in Stirling type PTC is one of the major developments reported in recent times, due to its simplicity of operation and improved performance over a period of time. Multistaging in cryocoolers is required to attain much lower temperatures [7]. PTCs are thermally coupled in series to form the multistage PTC. The first stage is employed to precool the second stage. Matrix with different sizes and materials can be employed depending on the operating temperature range, resulting in improved efficiency and lower cost. Cryocoolers are connected in series to reach the lower temperature region. One stage is used to precool the next stage. Single-stage Stirling type PTC can reach down to a temperature of 40-50 K, while temperatures around 20 K could be achieved by two-stage PTC. For

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below 10 K, three-stage PTC is used [8]. The very first two-stage Stirling type PTC is reported in the literature by Yang et al. [9]. The developed unit has coaxial geometry for both stages. Tendolkar et al. [10] done experimental investigations on an integral-configuration Stirling-type Two-Stage Pulse Tube Cryocooler (TSPTC). A double inlet valve is incorporated to the second stage with an inertance tube for the enhancement in the performance of the system. Dietrich and Thummes [11] developed a TSPTC for a cooling load of 12.9W at 25K. The specialty of this system is the use of cold head instead of the cold end heat exchanger in the first stage as no cooling is required at intermediate temperature. Wu et al. [12] achieved 15K with a cooling load of 0.3W.

Recent advancements in the multistaging of IPTC are the addition of step displacer as a phase shifter [13–16], Stirling/Pulse Tube Hybrid Cryocooler (SPC) [17], cryogenic phase-shifting mechanism [18], and cascading of cryocoolers [19]. Pang et al. [13, 14] added step displacer in two-stage PTC to enhance the performance. Integral structure type step displacer improved efficiency by 5.42%. Step displacer implements two functions, one is to distribute work between two stages and the second is to control phase shift. In the second stage of step displacer Two-Stage Inertance Pulse Tube Cryocooler (TSIPTC), the cyclic steady temperature of 16.9 K is attained at CHX experimentally [15, 16]. Raytheon Company developed an innovative SPC in 1999. SPC is made with a combination of Stirling cryocooler and PTC in the first and second stage respectively. SPC has the collective advantage of high efficiency and reliability from Stirling cryocooler and PTC respectively. That's the reason why SPC is suitable for space application. Liu et al. [17] developed SPC with cooling capacity of 1.16W at 35K and 7.25W at 85K. Dang et al. [18] used a cryogenic phase-shifting approach instead of an external precooling approach to avoid complexity in multistaging. In the case of the three-stage PTC,

inertance tube and reservoir of the third stage kept in cryogenic environment instead of ambient, which improves the performance of the system. Jeong and Jin [19] compared two-stage cryocooler and cascade cryocooler on the thermal performance basis and it is observed that cascading performs better when the temperature ratio is large.

For the design and optimization of PTC, there are different models accessible in the literature with certain benefits and some limitations. The experimental assessment of PTC is tremendously demanding and expensive, while analytical is a time-requiring assessment method. Most of the researchers developed different numerical models for analysis due to the accurate prediction of results. Isothermal model [20–22], adiabatic model [10, 23], energy equation model [24], and Computational Fluid Dynamics (CFD) model [25–27]. The isothermal model and adiabatic model are extensively used due to their simplicity. These models can give broad clarification by considering the real process occurring in the system to some extent. At lower cold end temperatures, it is found that the energy equation model can anticipate the cooling power performance of the PTC system sensibly well. CFD model can give detailed clarification about the real process occurring in the system and it predicts much more accurate results. Researchers have done CFD analysis of PTC for different geometrical and operational parameters with 2D axisymmetric [25, 26] and 3D plane-symmetric models [27, 28]. For optimization of PTC, CFD models [29] and various artificial intelligence methods like ANN, PSO-ANN, and ANFIS method are used to attain maximum refrigeration and Coefficient of Performance (COP) by giving an optimum range of inputs [30–32]. Panda et al. [32] revealed that refrigerating capacity and COP increased by 10.8% and 0.76% respectively.

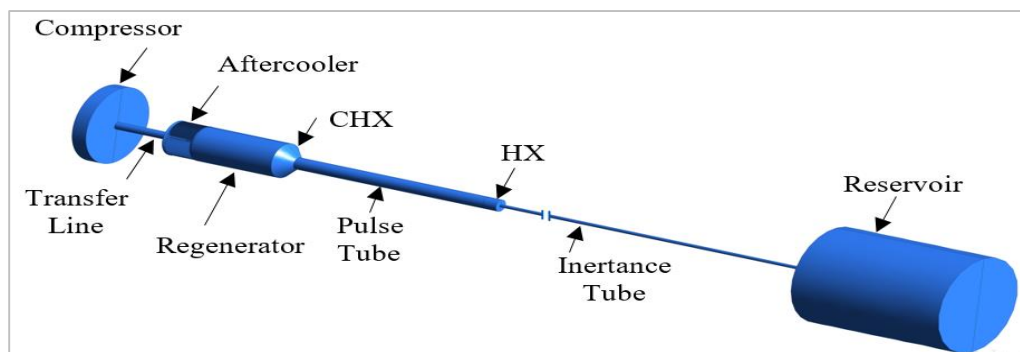


Figure 1 Inertance pulse tube cryocooler system

Exhaustive literature is available about single-stage configurations. However, very scanty data are available about the double inlet valve with multistage configurations in the literature. As per the author's knowledge, three-dimensional CFD modeling of multistaging with double inlet valve is not available in the literature. So, we get motivated and developed the methodology for the numerical investigation of multistaging PTC with the double inlet valve. The objective of the current study is to design a Double Inlet Two-Stage Pulse Tube Cryocooler (DITSPTC) for 20K cryogenic temperatures.

This paper performs CFD simulations of IPTC for defining the methodology using the CFD software package and then the same methodology is extended to the analysis of DITSPTC. For the assessment of DITSPTC and CFD was used as a numerical tool. Cha et al. [26] PTC model and Tendolkar et al. [10] DITSPTC model considered for the analysis. The system is simulated to evaluate the performance of the TSPTC with double inlet valve.

2. Methodology

CFD tools are extensively utilized for numerical simulation-based analysis of systems including fluid flow, heat transport, and associated chemical reaction phenomena. In PTC, a CFD is a very useful and valuable tool for predicting the mechanism of cold formation. Modeling of the compressor employing dynamic meshing with suitable "user-defined functions" is possible with CFD Fluid, liquid, Smooth and Unconstrained in Movement (FLUENT) software. Modeling of regenerators and heat exchangers using porous media is also possible with CFD.

Geometry formation, meshing, and FLUENT setup with appropriate boundary conditions and user-defined functions are all essential of the CFD analysis of the system. The energy equation is used to understand the heat transfer mechanism and cold formation, as well as the standard k-ε turbulence model to analyze the influence of turbulence kinetic energy. Helium is the working fluid for PTC, and copper and steel are the solids used for walls. Density, specific heat, thermal conductivity, viscosity, and diffusivity are all properties that can be defined in this section. In some circumstances, designers need to establish a special profile as a boundary condition, and these conditions cannot be specified using FLUENT's

default settings. FLUENT offers the user-defined function option for defining such conditions.

2.1 Governing equations

The continuity, momentum, and energy equation are the main governing equations employed. When fluid flows in the PTC, these *Equations 1, 2 and 3* must be satisfied. Conservation equations based on the continuum can be used throughout the PTC system. The mean free path of a gas molecule is often significantly less than the characteristic dimension of the PTC components.

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) = 0 \quad (1)$$

$$\frac{\partial}{\partial t} (\rho \vec{v}) + \nabla \cdot (\rho \vec{v} \vec{v}) = -\nabla p + \nabla \cdot (\bar{\tau}) \quad (2)$$

$$\frac{\partial}{\partial t} (\rho E) + \nabla \cdot (\vec{v}(\rho E + p)) = \nabla \cdot (k_{eff} \nabla T + (\bar{\tau}_{eff} \cdot \vec{v})) \quad (3)$$

The heat exchangers may be exceptions to the above statement in some cases. The microporous structure's characteristic dimensions are comparable to, or even less than, the mean free path. So, heat exchangers are modeled using the porous media method. Thus, governing *Equations 4 and 5* for the regenerator and heat exchangers.

$$\frac{\partial(\epsilon \rho)}{\partial t} + \nabla \cdot (\epsilon \rho \vec{v}) = 0 \quad (4)$$

$$\frac{\partial}{\partial t} (\epsilon \rho \vec{v}) + \nabla \cdot (\epsilon \rho \vec{v} \vec{v}) = -\epsilon \nabla p + \nabla \cdot (\epsilon \bar{\tau}) + S_i \quad (5)$$

Where S_i is an additional term for consideration of flow resistances in porous media and it is the combination of Darcy and Forchheimer term [33]:

$$S_i = -\left(\frac{\mu}{\alpha} v_j + C_2 \frac{1}{2} \rho v_{mag} v_j\right) \quad (6)$$

$$\alpha = \frac{D_p^2}{150} \frac{\epsilon^3}{(1-\epsilon)^2} \quad (7)$$

$$C_2 = \frac{3.5}{D_p} \frac{(1-\epsilon)}{\epsilon^3} \quad (8)$$

$$\frac{\partial}{\partial t} (\epsilon \rho_f E_f + (1-\epsilon) \rho_s E_s) + \nabla \cdot (\vec{v}(\rho_f E_f + p)) = \nabla \cdot (k_{eff} \nabla T + (\bar{\tau}_{eff} \cdot \vec{v})) \quad (9)$$

The theme of the current study is depicted in *Figure 2*. This paper performs CFD simulations of IPTC for defining the methodology using the CFD software package and then the same methodology is extended to the analysis of DITSPTC. The outcomes of system simulations are the cooldown curve, temperature contours, temperature along the length of the system, and the effect of double inlet valve opening on second stage CHX temperature

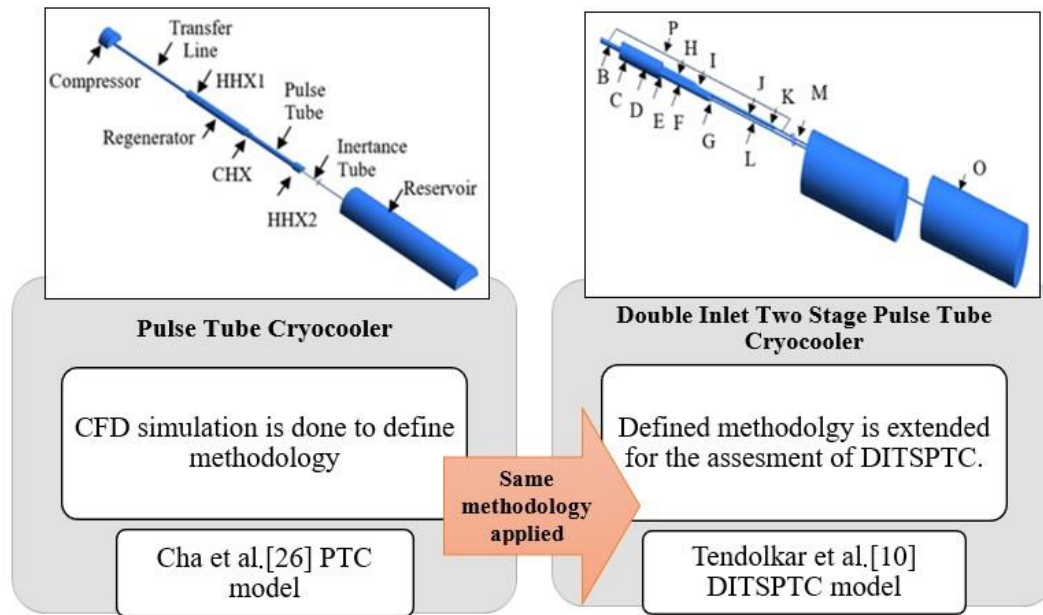


Figure 2 Theme of research paper

2.2 Pulse tube refrigerator model

Cha et al. [26] IPTC model is considered for the analysis. The simulations are done first using a 2D axis-symmetric model and then the same simulation is done using a 3D plane-symmetric model to get more insight into the complex processes occurring within the system.

2.2.1 Model building and mesh generation

The schematic diagram for IPTC contains all cylindrical components. This can be used to model the IPTC geometry as plane-symmetric about the common plane of all the components. The “Add Frozen” function is used instead of “Add Material” for geometry creation. This is required so that different components of IPTC do not merge into each other. The dimensions of the IPTC of Cha et al. [26] model are tabularized in Table 1. The mesh is generated using Analysis of Systems (ANSYS) workbench meshing. The elements used in the mesh are mainly hexahedral and triangular for some components. This is required

so that the mesh will match at the interfaces of the different components. Figure 3 and Figure 4 show the geometry created using a 2D axisymmetric and 3D plane-symmetric model.

The mesh is generated using ANSYS workbench meshing. The elements used in the mesh are mainly hexahedral and triangular for some components. This is required so that the mesh will match at the interfaces of the different components. The number of nodes and elements after meshing of PTC systems in the 2D axisymmetric model are 4253 and 3840 respectively, and in the 3D plane-symmetric model is 38711 and 46294 respectively. The meshing is done such that it will give the mesh-independent solution. The Mesh of different components in the 3D model is shown in Figure 5.

Table 1 Component dimensions of inertance pulse tube cryocooler

System	Radius (m)	Length (m)
Compressor	9.54×10^{-03}	7.50×10^{-03}
Transfer line	1.55×10^{-03}	1.01×10^{-01}
HHX1	4.00×10^{-03}	2.00×10^{-02}
Regenerator	4.00×10^{-03}	5.80×10^{-02}
CHX	3.00×10^{-03}	5.70×10^{-03}
Pulse tube	2.50×10^{-03}	6.00×10^{-02}
HHX2	4.00×10^{-03}	1.00×10^{-02}
Inertance tube	4.25×10^{-04}	6.84×10^{-01}
Reservoir	1.30×10^{-02}	1.3×10^{-01}

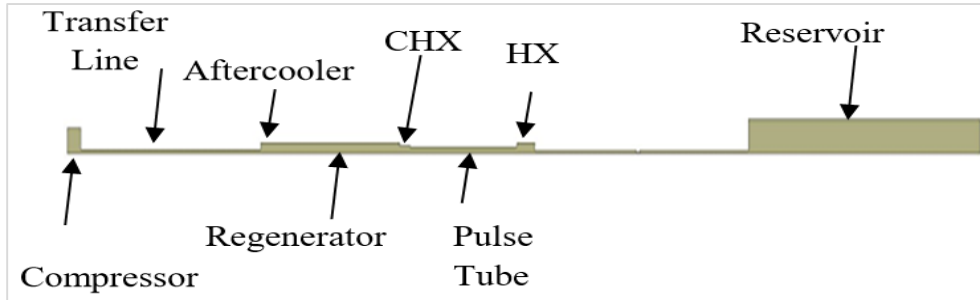


Figure 3 2D axisymmetric model of inertia pulse tube cryocooler

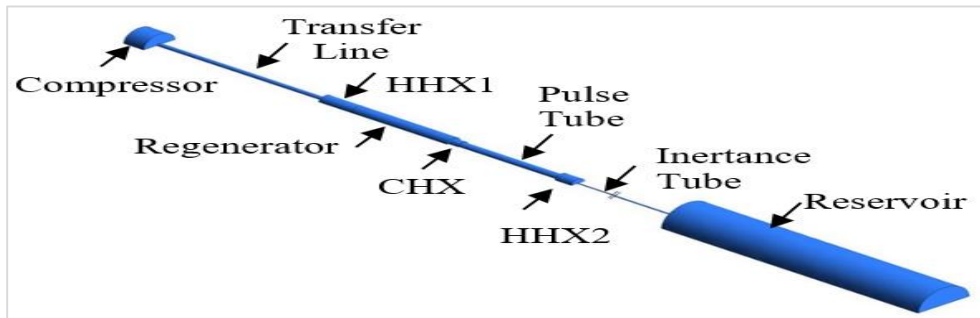


Figure 4 3D plane-symmetric model of inertia pulse tube cryocooler

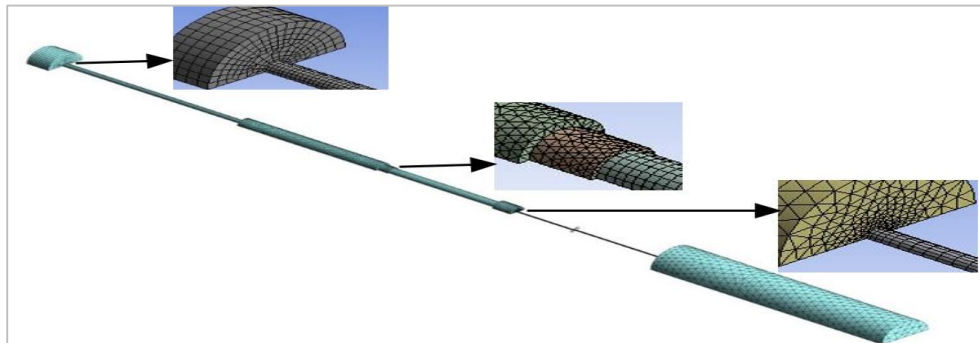


Figure 5 Mesh view of the 3D plane-symmetric mode

2.2.2 FLUENT setup

The FLUENT configuration for the current case is given in *Table 2*. In cell zone conditions, porous media can be defined for components such as aftercooler (Hot End Heat Exchangers (HHX)1), regenerator, and CHX and HHX2. The viscous (D) and inertial resistances (C) were found out for the porous zone section. The thermal equilibrium model is used in the porous zone. In the thermal equilibrium model, gas and wire mesh temperature considered the same at any time of instant. The walls of different components are also defined in the boundary conditions. The detailed cell zone and boundary conditions used to define the PTC are shown in *Table 3*.

There are some cases where the specific profile to be defined as a boundary condition and these conditions cannot be given through default options available in FLUENT. For defining such conditions, FLUENT provides the option of User-Defined Function (UDF). In the current case, it is achieved by giving velocity to the piston as shown in *Figure 6*. 100 inner steps with a time step size of 0.0003s are considered for better solution convergence. With a CPU combination of 4GB of RAM and 2.40 GHz processor, reaching a periodic steady-state takes over 30 days.

Table 2 FLUENT configuration and operating parameters

Solver	Pressure based solver
Computation	Double precision
Analysis	Transient
Turbulent and Energy Model	$\kappa - \epsilon$ and energy enabled
Solution Methods	SIMPLE scheme with second-order transient
Frequency	34 Hz

Table 3 Boundary conditions and cell zones

System	Cell zone	Boundary conditions
Compressor	Solid: Steel	Adiabatic
Transfer line	Solid: Steel	Adiabatic
HHX1	Porous zone: Copper, Porosity: 0.69 D: $9.44 \times 10^9 \text{ m}^{-2}$, C: 76090 m^{-1}	Wall Temperature is 300K
Regenerator	Porous zone: Steel, Porosity: 0.69 D: $9.44 \times 10^{10} \text{ m}^{-2}$, C: 76090 m^{-1}	Adiabatic
CHX	Porous zone: Copper, Porosity: 0.69 D: $9.44 \times 10^9 \text{ m}^{-2}$, C: 76090 m^{-1}	Adiabatic
Pulse tube	Solid: Steel	Adiabatic
HHX2	Porous zone: Copper, Porosity: 0.69 D: $9.44 \times 10^9 \text{ m}^{-2}$, C: 76090 m^{-1}	Wall Temperature is 300K
Inertance tube	Solid: Copper	Adiabatic
Reservoir	Solid: Steel	Adiabatic

```
#include "udf.h"
static real vely = 0.0;
DEFINE_CG_MOTION(velocityfinal, dt, vel, omega, time, dtime)
{
  real freq = 34.0;
  real w;
  w = 2.0 * M_PI * freq;
  NV_S(vel, =, 0.0);
  NV_S(omega, =, 0.0);
  vely = w * 0.004511 * cos(w * time);
  vel[0] = vely;
}
```

Figure 6 User defined function

2.2.3 Results of IPTC model

IPTC model is simulated and the results obtained from the simulation are compared with Cha et al. [26] model. The time-varying temperature at CHX is shown in *Figure 7*. The cyclic steady temperature achieved at CHX by 2D axisymmetric and 3D plane-symmetric modeling is 75.88 K and 76 K respectively. Results obtained from 2D axis-symmetric and 3D plane-symmetric models adequately agree with the results of Cha et al. [26]. The change between experimental and numerical analysis is due to the assumption of an ideal gas and no wall thickness consideration. So the single-stage IPTC is validated. The same methodology can be extended for the simulation of the double inlet two-stage IPTC. To study the temperature distribution in different

components, the temperature values are obtained at different locations along the centerline of the components. These values are the average value over a cycle for a particular location. The radial temperature variation in the different components is negligible. The temperature along the axial direction for the IPTC is displayed in *Figure 8*. During the PTC operation, pressurization in the compressor leads to an increase in pressure and temperature. The heat generated due to compression is rejected through the aftercooler which brings down the temperature to the ambient. The rest of the energy that is not rejected through the aftercooler is carried through by the enthalpy flow in the regenerator. Heat is rejected to the wire mesh resulting in the temperature reduction of helium gas.

Temperature increases along the length of the pulse tube due to pressure variation. The hot end heat exchanger is employed after the pulse tube to maintain ambient temperature. The backward flow occurs as a result of depressurization. Phase shift obtained between pressure and mass flow due to the phase-shifting mechanism resulting in the refrigeration at CHX. *Figure 9* shows the temperature contours for the components of IPTC which are, regenerator, CHX,

and pulse tube. The mass flow rate with pressure variation graph is crucial and useful for the optimization of the refrigeration effect. It is shown in *Figure 10*. The validation of the Cha et al. [26] model is done successfully and the same methodology is applied to double inlet two-stage PTC. The model that is used here for simulation and analysis is taken from Tendolkar et al. [10] DITSPTC model.

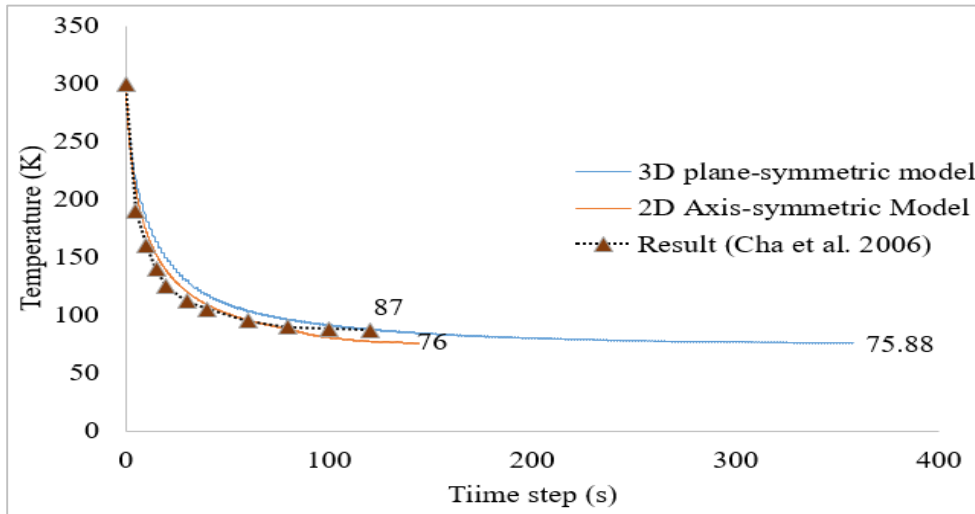


Figure 7 Cooldown curve of inertance pulse tube cryocooler

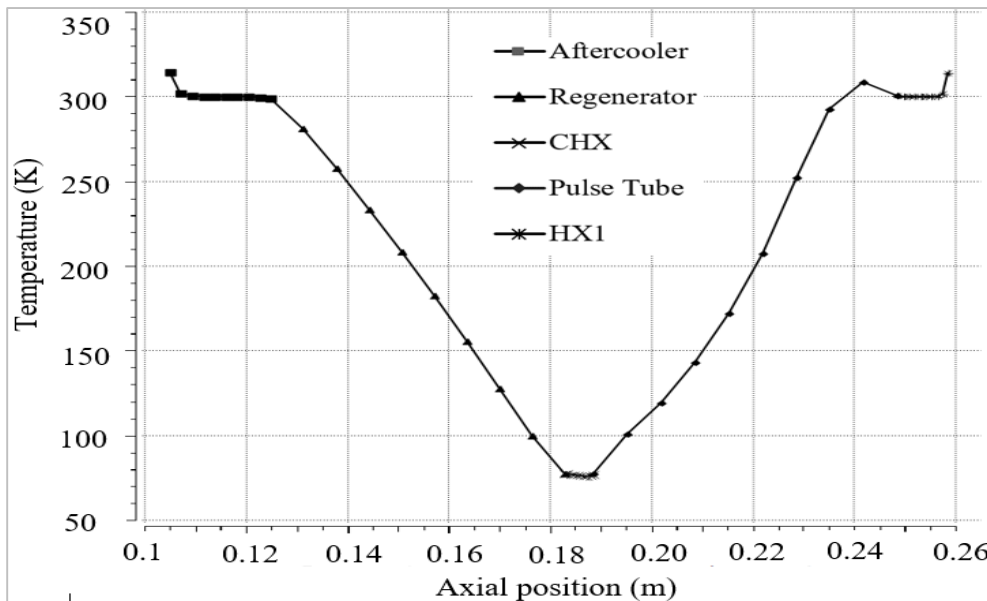


Figure 8 Temperature along the length of IPTC

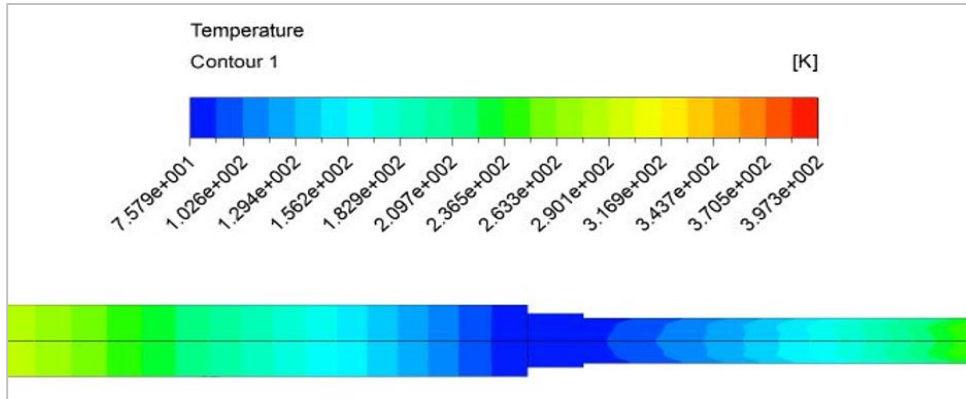


Figure 9 Temperature contour of inertance PTC

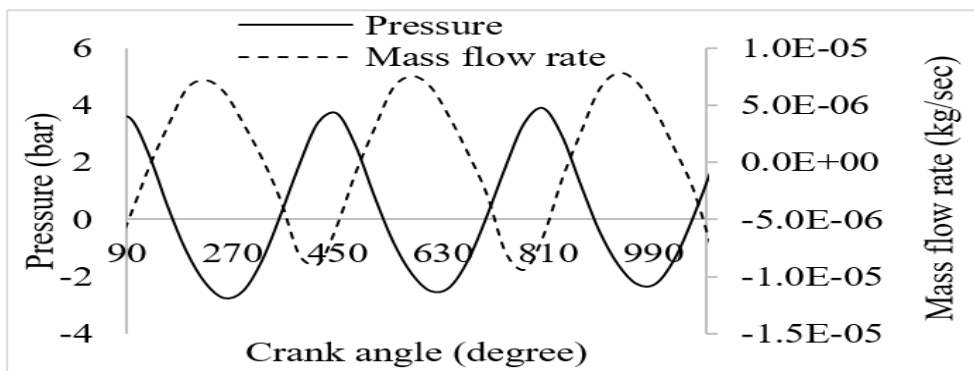


Figure 10 Pressure and mass flow variation at CHX

2.3 Double inlet two-stage inertance pulse tube cryocooler

The DITSPTC system consists of a double inlet valve and two stages of PTC. The double inlet valve optimizes the phase shift and the second stage gives the required cryogenic temperature. Tendolkar et al. [10] DITSPTC model is considered for the analysis. Numerical analysis of DITSPTC is done and validated with the experimental results obtained by Tendolkar et al. [10].

2.3.1 Model building and mesh generation

The 3D plane-symmetric model is generated using the ANSYS workbench. DI valve with 425 mm length and 1 mm diameter is incorporated between the transfer

line and hot end heat exchanger side of the second stage to improve the performance. The dimensions of the Tendolkar et al. [10] DITSPTC model are tabularized in Table 4. The DITSPTC model is shown in Figure 11. The optimal meshing for the DITSPTC is done using hexahedral and tetrahedron elements. The Mesh of different components in the 3D model is shown in Figure 12. The test for grid independency is done and the optimum number of nodes and elements after meshing of the DITSPTC system in the 3D plane-symmetric model are 450695 and 1027097 respectively. Figure 13 shows the grid independency test for the DITSPTC model.

Table 4 Dimensions of DITSPTC model

Component	Radius (m)	Length (m)
B (Transfer line)	3.00×10^{-03}	3.60×10^{-02}
C (Aftercooler)	1.00×10^{-02}	1.30×10^{-02}
D (Regenerator 1)	1.00×10^{-02}	5.50×10^{-02}
E (CHX 1)	1.00×10^{-02}	7.60×10^{-03}
F (Pulse tube 1)	4.00×10^{-03}	9.00×10^{-02}
G (HHX 1)	4.00×10^{-03}	1.00×10^{-02}
L (Inertance tube 1)	1.15×10^{-03}	2.00
N (Reservoir 1)	3.60×10^{-02}	1.76×10^{-01}

Component	Radius (m)	Length (m)
H (Regenerator 2)	4.50×10^{-3}	6.00×10^{-2}
I (CHX 2)	4.50×10^{-3}	1.12×10^{-2}
J (Pulse tube 2)	2.00×10^{-3}	1.20×10^{-1}
K (HHX 2)	2.00×10^{-3}	2.10×10^{-2}
M (Inertance tube 2)	1.15×10^{-3}	3.00
P(Double inlet valve)	0.5×10^{-3}	0.425
O (Reservoir 2)	3.60×10^{-2}	1.76×10^{-1}

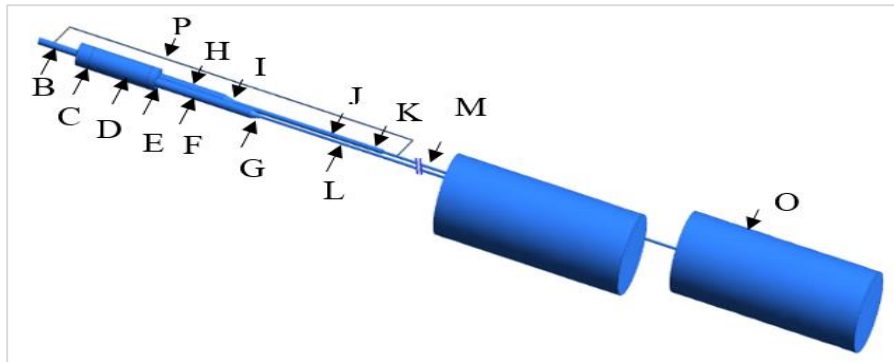


Figure 11 Double inlet two-stage inertance pulse tube cryocooler model

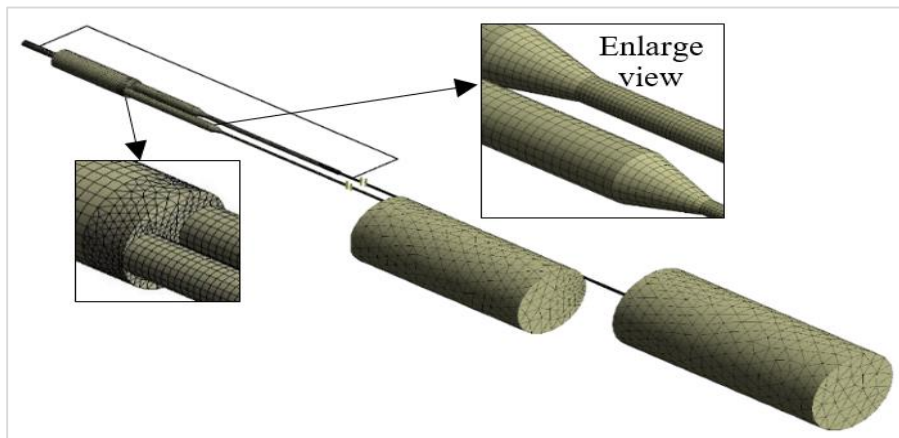


Figure 12 Mesh view of Double Inlet Two-Stage Inertance Pulse Tube Cryocooler (DITSIPTC)

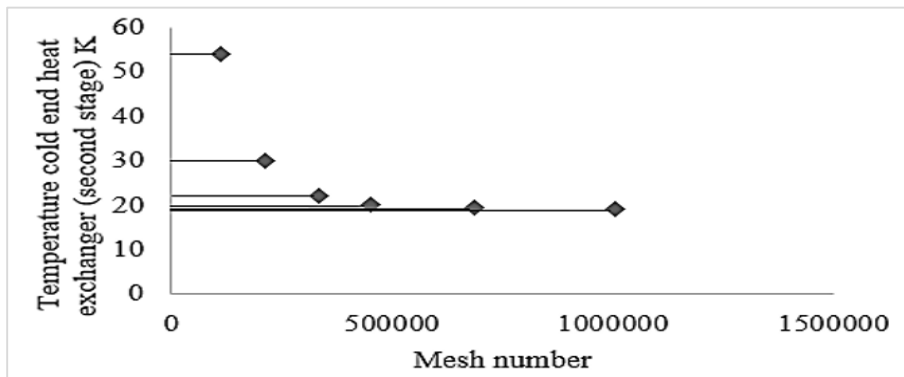


Figure 13 Mesh independency test

2.3.2 FLUENT setup

The FLUENT configuration for the current case is the same as the previous single-stage IPTC. Operating system pressure and frequency are 20 bar and 70 Hz respectively. In cell zone conditions, porous media can be defined for the heat exchangers. The viscous and inertial resistances are found out for the porous zone. There is continuous pressurization and depressurization occur in the system. So, the fluid flow

considered in the system is compressible. In all the components of the system, flow is considered laminar. The detailed boundary conditions and respective cell zones are shown in *Table 5*.

Complete list of abbreviations is shown in Appendix I.

Table 5 Boundary conditions and cell zones

System	Cell zone	Boundary conditions
Compressor,	Solid: Steel	Adiabatic
Transfer line	Solid: Steel	Adiabatic
Aftercooler (HHX1), HHX2 - stage one	Porous zone: Copper, Porosity (ϕ): 0.69 D: $1.2987 \times 10^9 \text{ m}^{-2}$, C: 9234 m^{-1} ,	Wall Temperature: 300K
Regenerator 1	Porous zone: Steel, Porosity (ϕ): 0.686 D: $2.083 \times 10^{10} \text{ m}^{-2}$, C: 34189 m^{-1}	Adiabatic
Regenerator 2	Porous zone: Steel, Porosity (ϕ): 0.607 D: $4.166 \times 10^{10} \text{ m}^{-2}$, C: 51707 m^{-1}	Adiabatic
CHX 1 and CHX 2	Porous zone: Copper, Porosity (ϕ): 0.69 D: $1.2987 \times 10^9 \text{ m}^{-2}$, C: 6905 m^{-1}	Adiabatic
Double Inlet Valve, Pulse Tube 1 and 2	Solid: Steel	Adiabatic
HHX 1 and HHX 2 - stage two	Porous zone: Copper, Porosity (ϕ): 0.691 D: $1.2987 \times 10^9 \text{ m}^{-2}$, C: 7883 m^{-1}	Adiabatic
Inertance tubes	Solid: Copper	Adiabatic
Reservoirs	Solid: Steel	Adiabatic

3. Results and discussions

The temperature variations of the first and second-stage cold end heat exchangers are plotted in *Figure 14*. For the first stage and second stage regenerators, 400 size wire mesh and 500 size wire mesh are used. The first stage CHX and second stage regenerator are thermally coupled. So, cooling at the second stage depends on the temperature of the first stage regenerator. The initial trends of cyclic temperature at CHX1 and CHX2 show that CHX1 temperature is decreasing at a faster rate than CHX2 temperature after 225 K, this is since there is a reduced mass flow through the second stage regenerator due to its finer mesh.

The simulation of DITSPTC was carried out till the cyclic steady temperature achieved at both the CHX1 and CHX2. Temperature contour is given to display the temperature in the DITSPTC system at a time instant. The temperature achieved at CHX1 is 95 K and at CHX2 is 20 K respectively, which are in close relation with experimental values of Tendolkar's DITSPTC 96 K and 23.56 K respectively shown in *Figure 15* and *Figure 16*. The temperature contour showing the temperature of DITSPTC at the cyclic steady state of the system. The cyclic steady

temperature at CHX1 and CHX2 are confirmed by both the cooldown curve and temperature contours. The temperature difference in the numerical and experimental analysis is induced due to the assumption of an ideal gas and no wall thickness consideration. Hence, the model has been successfully applied and validated to double inlet two-stage PTC.

The performance of the DITSPTC is strongly influenced by the setting of a double inlet valve at the second stage. The distribution of total gas from the compressor to the stages is significant since it is mostly governed by the area available through the double inlet valve. *Figure 17* shows the variation of second stage CHX temperature with the percentage opening of the double inlet valve. DITSPTC performs better when the double inlet valve fully open.

In CFD simulation of PTC and DITSPTC, the regenerator is modeled as the porous zone. Regenerator analysis can be done by using the thermal equilibrium model or thermal non-equilibrium model. The temperature of gas and wire mesh is considered as same at any instant of time in the thermal equilibrium model. For avoiding the complexity of the problem, the thermal equilibrium model is used. The present study considered fluid domain with no wall thickness.

In the near future, the numerical assessment of DITSPTC can be done by considering the thermal

non-equilibrium model and thickness of the wall to address the conduction losses.

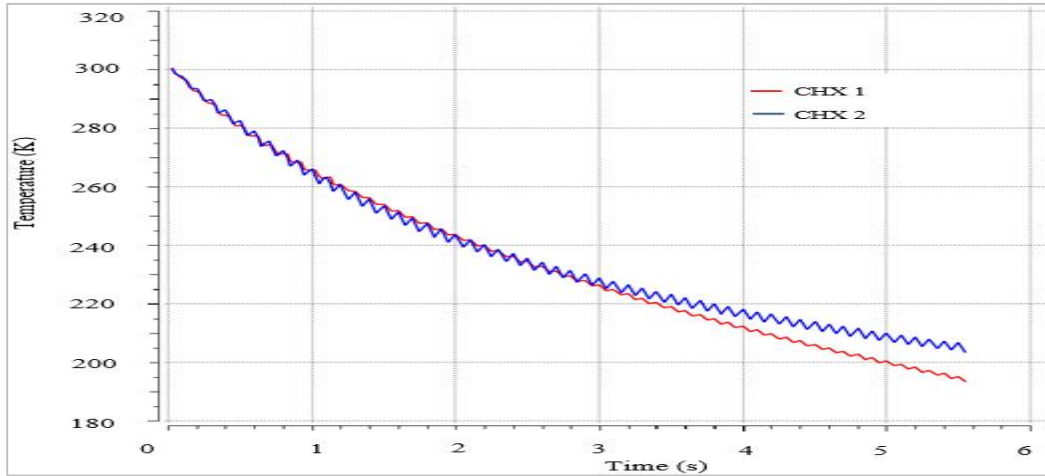


Figure 14 Initial trend of cooldown curve for CHX1 and CHX 2

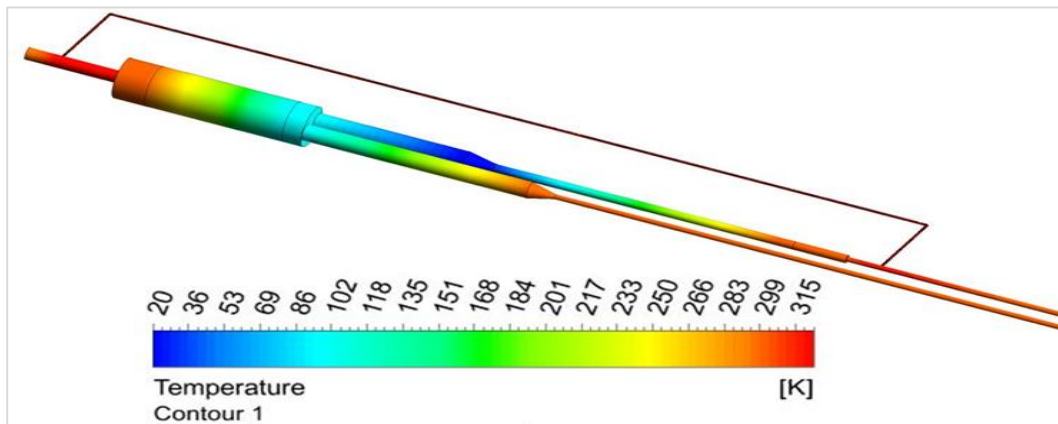


Figure 15 Temperature contour for DITSIPTC

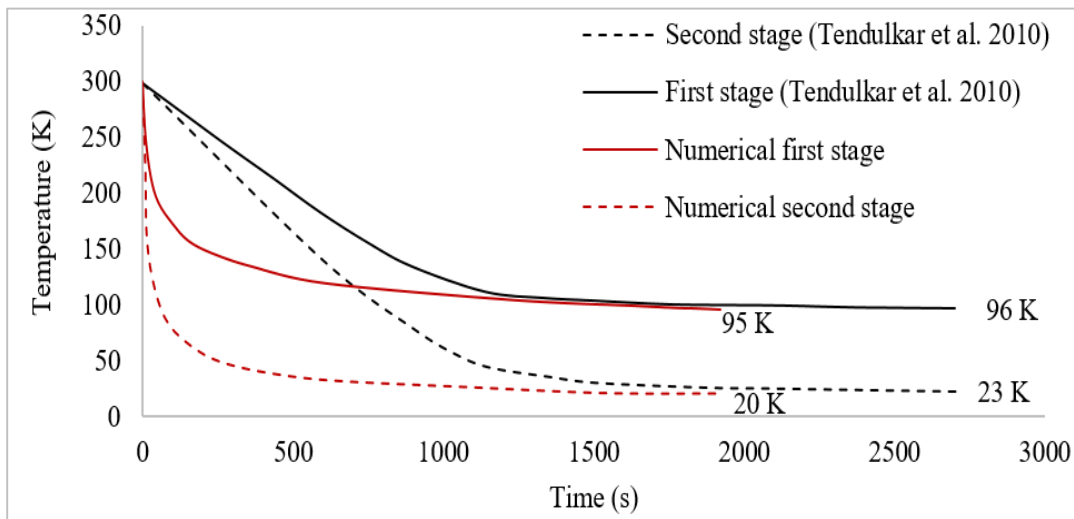


Figure 16 Cooldown curves for CHX1 and CHX2

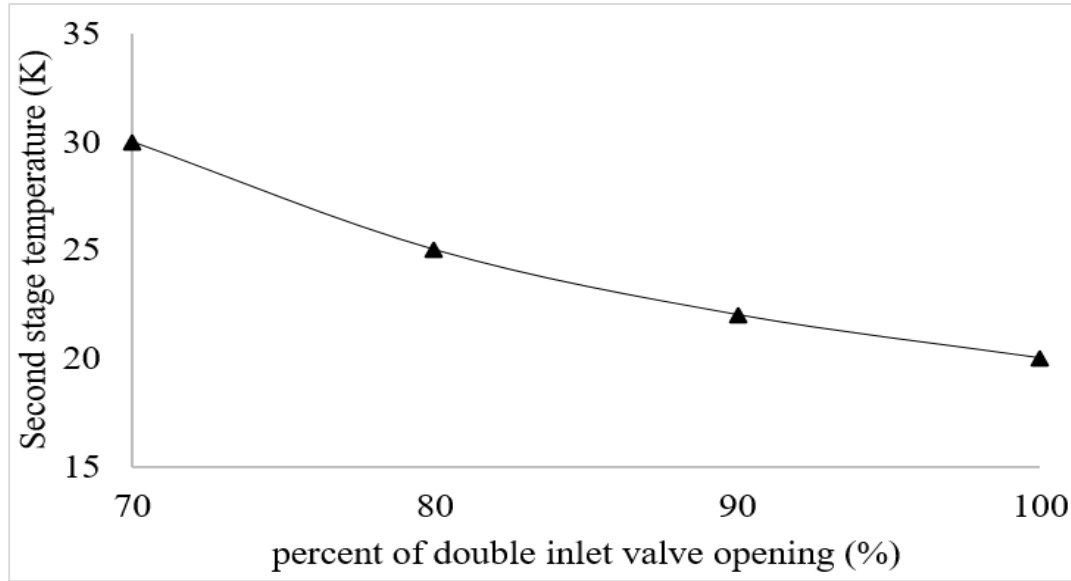


Figure 17 Second stage CHX temperature vs double inlet valve opening

4. Conclusion

The DITSPTC is numerically simulated using a 3D plane-symmetric model for the lowest attainable temperature. This study performed CFD simulations of PTC to define the approach, which is then extended to the analysis of a DITSPTC using the same methodology. CFD simulations of PTC yielded cyclic steady-state temperatures of 76 K and 75.88 K for the 2D axis-symmetric and 3D plane-symmetric models respectively. The proposed simulation methodology adequately agrees with the stated literature. The simulations are performed using the same methodology for DITSPTC at the frequency of 70 Hz and average pressure of 20 bar. At the first and second stages, simulations yielded minimum temperatures of 95 K and 20 K, respectively. CFD simulations are following experimental results of reported literature adequately. The performance of the DITSPTC is strongly influenced by the setting of a double inlet valve in the second stage. The system functions best when the double inlet valve is fully opened. The proposed methodology can be reckoned to simulate the PTC during the system design phase, as per the above analysis.

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Conflicts of interest

The authors have no conflicts of interest to declare.

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Appendix I

S.No.	Abbreviation	Description
1	ANFIS	Artificial Neuro Fuzzy Inference System
2	ANN	Artificial Neural Network
3	ANSYS	Analysis of Systems
4	CHX	Cold End Heat Exchanger
5	CFD	Computational Fluid Dynamics
6	COP	Coefficient of Performance
7	CPU	Central Processing Unit
8	DI	Double Inlet
9	DIPTC	Double Inlet Pulse Tube Cryocooler
10	DITSIPTC	Double Inlet Two-Stage Inertance Pulse Tube Cryocooler
11	DITSPTC	Double Inlet Two-Stage Pulse Tube Cryocooler
12	FLUENT	Fluid, Liquid, Smooth and Unconstrained in Movement
13	HHX1 and HHX2	Hot End Heat Exchangers
14	HX	Hot Heat Exchanger
15	IPTC	Inertance Tube Pulse Tube Cryocooler
16	OPTC	Orifice Pulse Tube Cryocooler
17	PSO	Particle Swarm Optimization
18	PTC	Pulse Tube Cryocooler
19	RAM	Random Access Memory
20	SPC	Stirling/Pulse Tube Hybrid Cryocooler
21	TSIPTC	Two-Stage Inertance Pulse Tube Cryocooler
22	TSPTC	Two-Stage Pulse Tube Cryocooler
23	UDF	User Defined Function

Nomenclature

		Greek symbols
C_2	Inertial resistance factor	α Permeability
E	Total energy of the fluid	ϵ Void number
E_f	Fluid energy	\vec{v} Velocity
E_s	Solid medium energy	$\bar{\tau}$ Stress tensor
k_{eff}	Effective thermal conductivity	ρ Fluid density
P	Static pressure	
T	Temperature	