

Design a new wire cut EDM machine for turning operation

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Abstract

Advanced and complex materials machining are the biggest problem in present industries. Advanced and complex materials used in different application like super alloys, tool, steels, ceramics, and composites with the need of high accuracy and good surface finishing. Its material very harder, so material removal is very harsh. This challenge can be solved by unconventional machining processes. The unconventional machining machine is machining the material to achieve high accuracy, reduce the material removal time and respectable surface finishing on the surface of the material. Wire cut electrical discharge machining (WEDM) is less used in turning operation in now a day. So, in this research, design and develop a new turning WEDM machine. In developed turning WEDM, different parameters effect on machining on turning operations. So, some parameters are investigated in this research. Experiments investigate the effect of varying peak current, infeed and revolution per minute of spindle on GCr15 material to examine the influence on the material removal rate (MRR) using ANOVA analysis. In the experiment, L27 orthogonal array is chosen for full factorial design of experiment (DOE) to manner analysis. The ANOVA calculation by both mathematical steps and design expert software. The Experimental outcome shows that the maximum material removal rate is 4.2 mm³/min at 90µm rotational infeed.

Keywords

CWEDM, ANOVA, MRR, Mathematical modelling, Turning operation.

1.Introduction

Wire cut electrical discharge machining (WEDM) is popular in manufacturing industries for profile cutting of harder or complex material or parts. Its thermal erosion machining process capable of harder and complex parts with higher accuracy. In WEDM removed material by applying spark heat and erosion system. WEDM is an unconventional machining process using thermal and electrical power which erodes the material from harder components by creating an ionized column between components and electrode, whole affected area sinks in liquid electrical fluid as shown in *Figure 1* [1]. Now days, the WEDM research area is wider. Several researchers have used WEDM in hybrid material removal mechanism. WEDM also used for cylindrical material removal. Qu et al. [2, 3] introduce a design of an accurate, springy and corrosion protected underwater rotary spindle. This error analysis done by frequency spectrum and found a major source of error is frequency spectrum.

Researchers gain maximum material removal rate (MRR) is 69.6mm³/min for brass material and 20.9 mm³/min for Carbide material. Balamurli et al. [4] worked on wire cut electrical discharge machine for cylindrical parts development and study different effects on material removal rate and surface finishing. Research is found max MRR 2.87mm³/min for SS316 Material. Also found MRR is most significantly influenced by rotational speed with a maximum value of MRR as 2.189 mm³/min at 500 RPM.

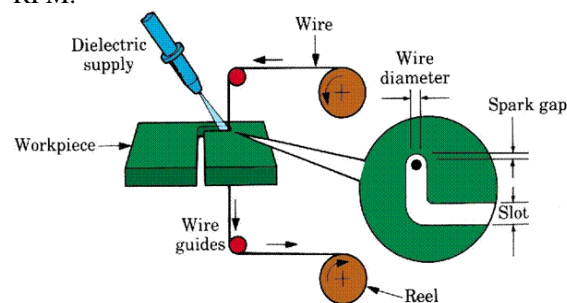


Figure 1 Schematic representation of WEDM cutting process

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Baki et al. [5] also develop rotary setup and give optimal combination process variable obtained from the proposed methods is the set with spindle speed-30rpm, pon-10 μ m, poff-50 μ m, peak current-150A, wire feed-3mm/min and servo-90V. An experiment is found max MRR 9.756mm³/min for Ti-6Al-4V material. Haddad et al. [6] also develop rotary setup and show that design of experiment (DOE) useful for experiment. An experiment is found max MRR 13.04 mm³/min for D3 Steel Material. Mohammadi et al. [7] introduced the design of a precise, flexible and corrosion-resistant rotary spindle submerged. An experiment is found maximum MRR is 63.799 mm³/min for cemented steel. Haddad and Tehrani [8] also design rotary setup and found maximum MRR is 14.92 mm³/min for D3 Steel. Zhu et al. [9] also develop rotary setup and found maximum MRR is 3.09 mm³/min for GCr15 Material. Mohammadi et al. [10] gives the ultrasonic vibration effects on wire in wire electrical discharge turning machine on complex machining material. Research also shows the machining parameters performance and accomplish the maximum material removal rate was 2.08026mm³/min. Janardhan and Samuel [11] developed an economical and a modest rotary spindle for turning a component in WEDM. The experiment was found maximum MRR is 9.75mm³/min for Brass Material. Gong et al. [12] to develop low speed wire electrical discharge turning. This research work study on effect of surface roughness.

Chen et al. [13] developed a new type rotary spindle have different capabilities in cylindrical machining like rough, semi-finish, and finish machining. They also studied the two parameters, material removal rate and surface roughness. The experiment was found the maximum MRR is 4.79965x 105 μ m³/min for cemented carbide k15 material. Krishnan and Samuel [14] discussed in the research on material removal model for improving the productivities. They introduced the adaptive neuro-fuzzy inference system for artificial neural network with feed-forward back-propagation algorithm for finest modelling. The experiment was found maximum MRR is 3.78mm³/min. Mohammadi et al. [15] used the ultrasonic vibration in cylindrical parts machining

in WEDM. The experiment result shows the combined effects are most significant in turning the material. Experimental setup is truthful, flexible, carrion protected and capable to work under dielectric fluid. Experimental results were also found maximum MRR is 3.03mm³/min for HSS material. Parthiban et al. [16] developed a rotary spindle unit and found maximum MRR is 4.52 mm³/min for tungsten carbide. Zhu et al. [17] developed the rotary setup large aspect-ratio rotational parts machining in WEDM. The setup worked under two stages, polygon sectional feeding strategy and final rapid contouring method and find faster material removal on components. They found maximum MRR is 26.25 mm³/min for nickel based elastic alloy 3J40 material.

2.Design of cylindrical wire cut EDM

In this research all the calculative design and modelling have been done. This machine basically divided into five divisions likes, wire feed mechanism, CNC table, pulse generator, control system and workpiece holding device.

The calculative design and modelling are shown in *Figure 2* and *Figure 3*. Workpiece holding device rotates the workpiece as per control signal. Workpiece holding device modelling and development is shown in *Figure 4* and *Figure 5*.

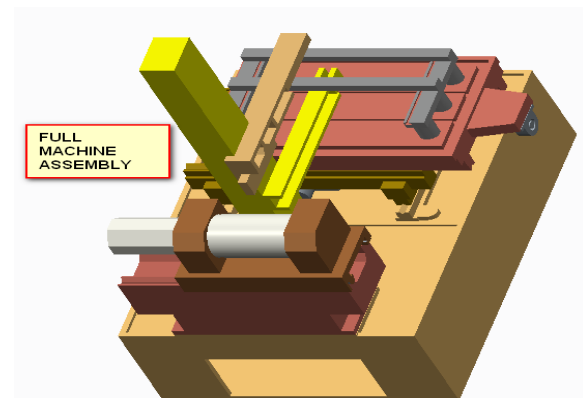


Figure 2 Modelling of new cylindrical wire cut EDM



Figure 3 Development of new cylindrical wire cut EDM

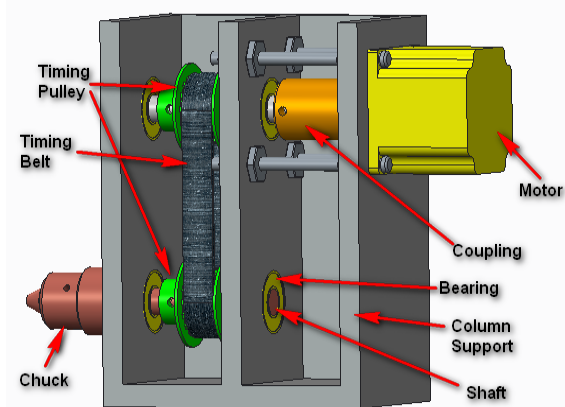


Figure 4 Modelling of the cylindrical workpiece holding device

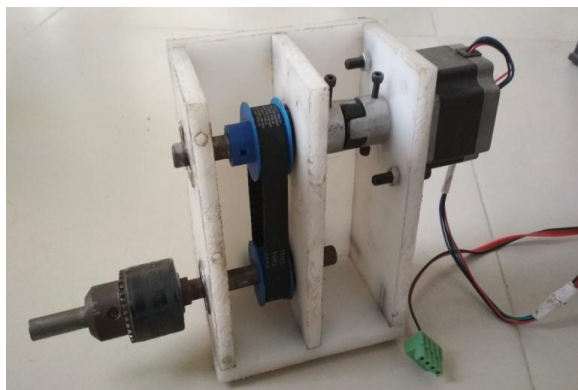


Figure 5 Development of new workpiece holding device

3. Experimental planning

3.1 Material specification

Wire-cut EDM is ordinarily utilized when low remaining anxieties are wanted, on the grounds that it doesn't require high cutting powers for expulsion of material.

Table 1 Material specification: GCr15

Chemical	Obtained value (%)	Required value
Carbon	0.98	0.95-1.10
Silicon	0.25	0.15-0.35
Manganese	0.30	0.20-0.40
Chromium	1.50	1.35-1.60
Molybdenum	0.09	Max 0.10
Phosphorus	0.021	Max 0.025
Sulfur	0.10	Max 0.10

GCr15 is a bearing steel. This can be utilized in the toughened condition. GCr15 offers high consumption obstruction, wear quality and high hardness. The GCr15 material tested in Divine Laboratories, Ahmedabad for chemical composition as shown in *Table 1*.

GCr15 Material generally used in higher toughness requirements like gear box of the supercharger, rear axle, greatly clip of spring load, pipe joining in oil industries and different cutting finish tools etc.

Researchers after a long work in wire electrical discharge machine have find notorious two types machining parameters, electrical factors (ON, OFF, peak current (IP), the spark voltage (SV)) and nonelectrical factor (wire tension, wire speed, dielectric pressure) was critically affected on output performance parameters of machining. Material thicknesses have little effect on MRR and spindle rotation (SR as RPM) as it remains constant by varying parameter this carrying on literature review. On WEDM main problem in selection of the level depends on wire breakage.

Few parameters are taken as a varying parameter while some kept as constant as per the shop floor engineer's opinion and based on referring machine operating manual and literature survey. Wire

consumption is the dominant issue. By keeping constant feed rate and peak current in this research work the varying parameter effect should be checked. Fixed parameter values are set based on trial run experiments. Fixed parameters set at values which remain constant throughout all experiments. Though these parameters can vary, but here it kept constant and then check the effect of control parameters. The reason to make a parameter constant based in the study of the operator setting phenomenon. *Table 2* shows the fixed parameters.

Table 2 Fixed parameters

Fixed parameter	Set value
Wire material	Brass

Table 3 Control parameters

Sr. No.	Machine parameter	Unit	Level		
			1	2	3
A	IP	Amp	1	2	3
B	RPM	RPM	20	40	60
C	If	µm	30	60	90

Table 4 Coded form of control parameters

Factor	Name	Type	Sub type	Mini mum	Maxi mum	Coded	Values	Mean	Std. Dev.
A	IP			1	3	-1 =1	1 =3	2	0.816497
B	RPM	Numeric	Continuous	20	60	-1 =20	1 =60	40	16.32993
C	If			30	90	-1 =30	1 =90	60	24.4949

3.3 Specimen detail

Total 27 experiments have been conducted by turning on round bar 3 mm diameter and 30 mm length machining up to 1 mm diameter and 10 mm length of GCr15 material.

4. Analysis and results

4.1 Experimental table

Experiment results shown in *Table 5*.

4.2 Regression analysis

- Using design expert software, the regression equation was determined and the plot of actual predictive value was made.
- The regression formula was found using the design expert software and the regression equation is given below:

Table 5 L27 orthogonal array of experiments with results

Std	Run	A: IP	B: RPM	C: Infeed	MRR
10	1	1	20	60	1.8
21	2	3	20	90	3.1
8	3	2	60	30	2.3
3	4	3	20	30	2.1
24	5	3	40	90	3.5
13	6	1	40	60	2

Fixed parameter	Set value
Peak current (IP)	1
Pulse peak voltage	8
Servo feed setting	2100

3.2 Input parameters and their levels

- A level 3 factor design was developed by using full factorial method.
- Design expert software has been used to design the orthogonal array.
- The level for the input parameters selected are IP, Infeed (If) and RPM as shown in *Table 3* and *Table 4*.
- L27 orthogonal array of full factorial DOE design have been used.

Final equation in terms of actual factors

$$\begin{aligned}
 MRR = & -0.71481 + (0.73333 \times Ip) + (5.55556E - 003 \times RPM) \\
 & + (0.038519 \times Infeed) + (5.83333E - 003 \times Ip \times RPM) \\
 & + (8.33333E - 004 \times Ip \times Infeed) + (1.11111E - 004 \times RPM \times Infeed) \\
 & - (0.10556 \times Ip^2) - (5.55556E - 005 \times RPM^2) - (2.28395E - 004 \times Infeed^2)
 \end{aligned}$$

The R-Sq (R²) esteem shows that the indicators clarify 98.18% of the change in MRR.

- The R-Sq (adj) (balanced R²) is 97.22%, which represents the quantity of indicators in the model. The two qualities demonstrate that the model fits the information well as shown in *Figure 6*.

Std	Run	A: IP	B: RPM	C: Infeed	MRR
20	7	2	20	90	2.4
17	8	2	60	60	3.3
27	9	3	60	90	4.2
15	10	3	40	60	3.2
18	11	3	60	60	3.7
16	12	1	60	60	2.3
9	13	3	60	30	2.9
14	14	2	40	60	2.9
4	15	1	40	30	1.4
6	16	3	40	30	2.6
2	17	2	20	30	1.6
12	18	3	20	60	2.8
19	19	1	20	90	2.2
7	20	1	60	30	1.6
5	21	2	40	30	2.1
22	22	1	40	90	2.2
23	23	2	40	90	3.3
25	24	1	60	90	2.7
1	25	1	20	30	1.2
26	26	2	60	90	3.5
11	27	2	20	60	2.3

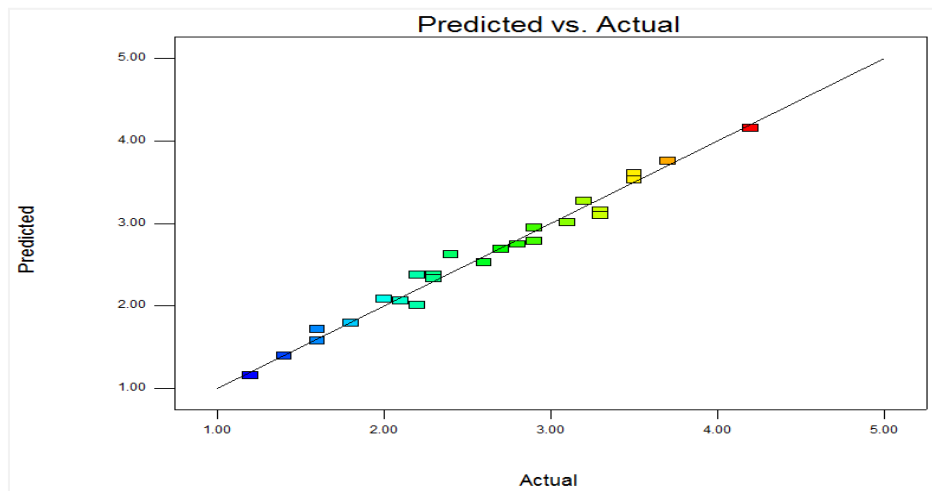


Figure 6 Actual vs. predicted value graph

4.3 Analysis of variance (ANOVA)

➤ ANOVA shows the parameter effect in percentage form as shown in Table 6.

The resolution of the factorial design permits us to estimate all the main effects and factor interactions. Factual programming was executed to plan the tests and examine the exploratory discoveries.

Investigation of fluctuation (ANOVA) has been regularly tried, since it covers the deficiency of graphical evaluation.

All three parameters are significant and most effected parameter in IP (44.06%) and RPM (18.86%), and If (33.29%). Residual is found very less that is 1.82%.

Table 6 ANOVA results of experiments

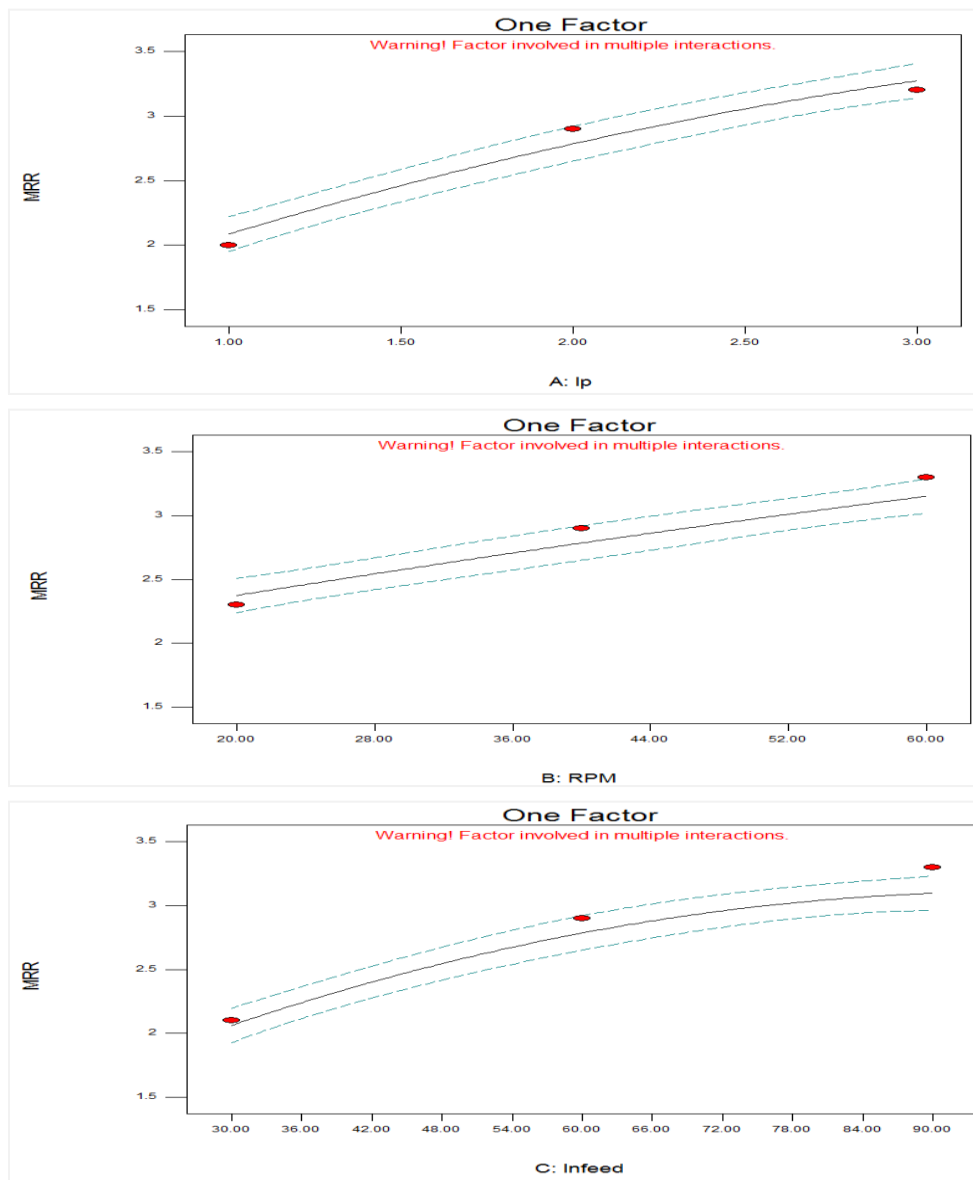
Source	Sum of squares	Df	Percentage
Model	14.43528	9	-
A-IP	6.360556	1	44.06
B-RPM	2.722222	1	18.86
C-Infeed	4.805	1	33.29
AB	0.163333	1	1.13

Source	Sum of squares	Df	Percentage
AC	0.0075	1	0.05
BC	0.053333	1	0.37
A^2	0.066852	1	0.46
B^2	0.002963	1	0.02
C^2	0.253519	1	1.76
Residual	0.267685	17	1.82
Cor Total	14.70296	26	100

4.4MRR results

Figure 7 demonstrates that IP, RPM and If have the huge impact on MRR. What's more, the IP, RPM and If have direct extent of MRR change; that is, by expanding IP, RPM and If, MRR increments

fundamentally. The effect of interaction between parameter is very less in MRR found.



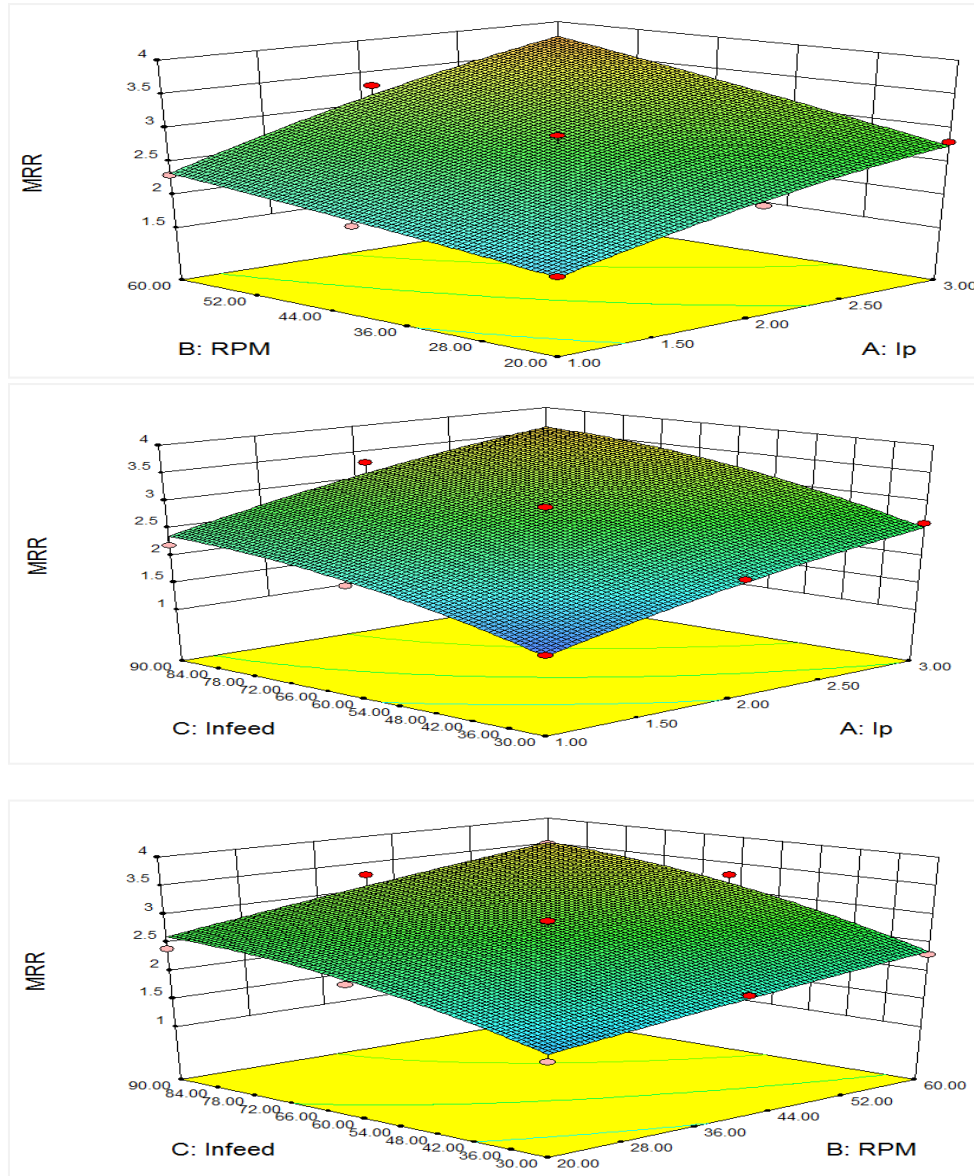


Figure 7 Plots of individual factor effects and interaction effects of changes of MRR

5. Conclusion

Material to make exact complex formed cylindrical shaped parts in both large scale and miniaturized scale level by applying a rotational axle on a typical wire EDM machine. So as to explore the ideal thickness of layers in the discretization procedure, a solitary factor try was directed to examine the connection between spiral if and MRR. The consequences of trial demonstrate that the greatest estimation of MRR can accomplish $4.2 \text{ mm}^3/\text{min}$ when the spiral If was $90\mu\text{m}$.

This examination presents an investigation of different procedure parameters and reached following determinations from the trial think about:

- Procedure parameters influence distinctive reaction in various ways. Thus, need to set a parameter dependent on prerequisite.
- If IP, SR and If value increase then the value of MRR also increase.
- IP parameter is the most significant factor.

Acknowledgment

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Conflicts of interest

The authors have no conflicts of interest to declare.

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